



Dimensions in mm.

| Electrical Data | Symbol | 22ECP60 8B-90.01 | Unit |
|--|-------------|------------------|--|
| 1 Nominal Voltage | U_N | 24 | Volt |
| 2 Optimization Direction | - | Symetrical | - |
| 3 No Load Speed | n_0 | 8,050 | rpm |
| 4 Typical No Load Current | I_o | 40 | mA |
| 5 Max. Continuous Mechanical Power (@25°C) | P_{max} | 120 | W |
| 6 Max. Continuous Current | $I_{e,max}$ | 1.8 | A |
| 7 Max. Continuous Torque | $M_{e,max}$ | 50.5 (7.16) | mNm (oz-in) |
| 8 Back EMF Constant | k_E | 2.96 | V/1000 rpm |
| 9 Torque Constant | k_M | 28.3 | mNm/A |
| 10 Motor Regulation | R/k^2 | 3.0 | 10 ³ /Nms |
| 11 Motor Regulation | $k/R^{1/2}$ | 18.3 (2.6) | mNm/W ^{1/2} (oz-in/W ^{1/2}) |
| 12 Internal Resistance - phase to phase | R_1 | 2.38 | ohms |
| 13 Line to Line Resistance at Connectors | R_L | 2.47 | ohms |
| 14 Inductance Phase to Phase | L | 0.48 | mH |
| 15 Mechanical Time Constant | τ_m | 1.0 | ms |
| 16 Electrical Time Constant | τ_e | 0.20 | ms |

| General Data | | | |
|---|-----------|-----------------------------|-------------------|
| 17 Maximum Motor Speed | n_{max} | 38000 | rpm |
| 18 Ambient Working Temperature Range | - | -30 to + 100 (-22 to + 212) | °C (°F) |
| 19 Ambient Storage Temperature Range | - | -40 to + 100 (-40 to + 212) | °C (°F) |
| 20 Ball Bearings Preload | - | 5.50 | N |
| 21 Axial Static Force w/o Shaft Support (max) | - | 34 | N |
| 22 Maximum Winding Temperature | - | 125 (257) | °C (°F) |
| 23 Thermal Resistance | R_{th} | 1/8.4 | °C/W |
| 24 Thermal Time Constant | τ_w | 1100 | s |
| 25 Weight | - | 140 (4.94) | g (oz) |
| 26 Rotor Inertia | J | 3.5 | g-cm ² |
| 27 Hall Sensor Electrical Phasing* | - | 120 | Electrical ° |

*Available without hall sensor

| Wire | Description |
|--------|---------------|
| Gray | Phase 1 |
| Violet | Phase 2 |
| Blue | Phase 3 |
| Green | 3.5 to 24V DC |
| Yellow | GND |
| Orange | Sensor 1 |
| Red | Sensor 2 |
| Brown | Sensor 3 |

with hall effect sensor

